

Efficient preconditioners for the solution of a Regularized Digital Image Correlation (RDIC) problem

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Mathematical formulation of the DIC problem

The Digital Image Correlation [Bay et al, 1999] (DIC) problem is formalized as the non-linear optimization problem, namely the grey level conservation law,

$$\min_{\mathbf{u} \in L^2(\Omega)} \phi(\mathbf{u}) = \int_{\Omega} [f(x) - g(x + \mathbf{u}(x))]^2 dx. \quad (1)$$

with $\Omega \subset \mathbb{R}^2$ or \mathbb{R}^3 the domain of interest, f, g the greyscale image of respectively the reference and the deformed specimen, and $u \in L^2(\Omega)$ the unknown displacement field.

Solution of the grey level conservation equation

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$$A\delta u^{(k)} = b^{(k)} \quad \text{with} \quad \begin{cases} A_{i,j} = \int_{\Omega} N_i^T \nabla f(x) \nabla f(x)^T N_j dx \\ b_i^{(k)} = \int_{\Omega} N_i^T \nabla f(f(x) - g(x + \mathbf{u}^{(k)})) dx \end{cases} . \quad (2)$$

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Hence the need to solve a **sequence of linear systems involving a symmetric positive definite A, of order #DOFs.**

Regularization of the problem

The problem (1) might need a regularization term to lower the measurement uncertainty,

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Different regularizations (Tikhonov, elastic) yield different matrices R , and finding the optimal value for α is not trivial.

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Method and features

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- the system is of very large scale,
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Let $A, M \in \mathbb{R}^{n \times n}$ be two s.p.d. linear operators, and $b, x_0 \in \mathbb{R}^n$. Let $r_0 = b - Ax_0$ denote the initial residual. The preconditioned conjugate gradient [Hestenes et al, 1952] yields after p iterations,

$$x_p = x_0 + \arg \min_{y \in K_p} \|x^* - y\|_A,$$

with $x^* = A^{-1}b$ the exact solution, and Krylov subspace K_p ,

$$K_p = \text{span} \left\{ Mr_0, (MA)Mr_0, \dots, (MA)^{p-1}Mr_0 \right\}.$$

Efficient preconditioner

The design of an efficient preconditioner [Wathen, 2015] is complex and mostly problem dependent. However, elementary algebraic preconditioners exist and can be easily implemented and tested.

An efficient preconditioner must ideally,

- Be cheap to construct and to store,
- Be cheap to apply to a vector ($M \approx A^{-1}$) or solve for a vector ($M \approx A$),
- Eventually be matrix-free,
- Allow parallelization.

Algebraic Preconditioners

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- Algebraic Multigrid used as preconditioners [Trottenberg et al, 2001],
- Domain Decomposition preconditioners [Dolean et al, 2015],
- Projection-based preconditioners: **Deflation** [Frank et al, 2001].

Deflation technique

Let $\mathcal{S} \subset \mathbb{R}^n$ and $S \in \mathbb{R}^{n \times k}$ such that $\mathcal{S} = \text{span}\{S\}$ be a block vector matrix and let us consider,

$$\pi_A(\mathcal{S}) = S(S^T A S)^{-1} S^T A.$$

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The solution of $Ax^* = b$ can be written $x^* = S(S^T A S)^{-1} S b + \tilde{x}$ with,

$$(I_n - \pi_A(\mathcal{S}))^T A \tilde{x} = (I_n - \pi_A(\mathcal{S}))^T b. \quad (3)$$

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The so-called deflated linear system is such that,

- The deflated operator is symmetric positive semi-definite and the system is consistent,
- The operator null space is \mathcal{S} ,
- $\kappa((I_n - \pi_A(\mathcal{S}))^T A) \leq \kappa(A)$.

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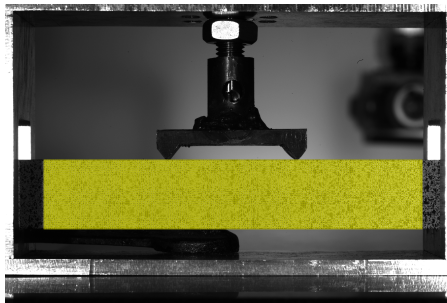
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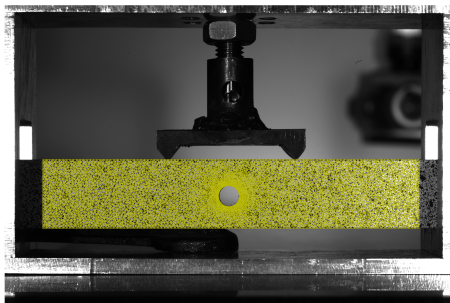
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Investigated problems

Two different cases are studied here:



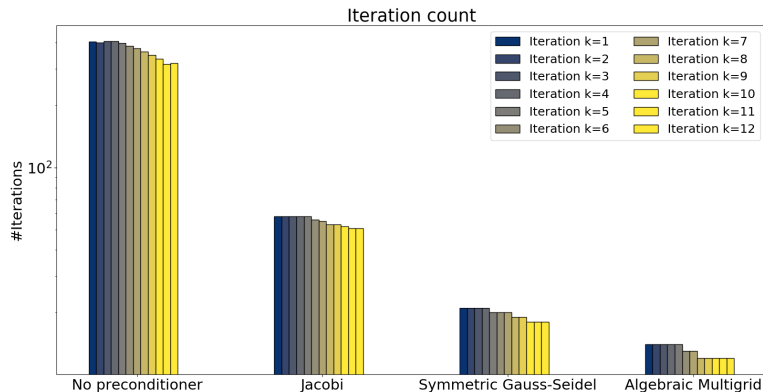
(a) High resolution mesh $n \approx 10^5$.



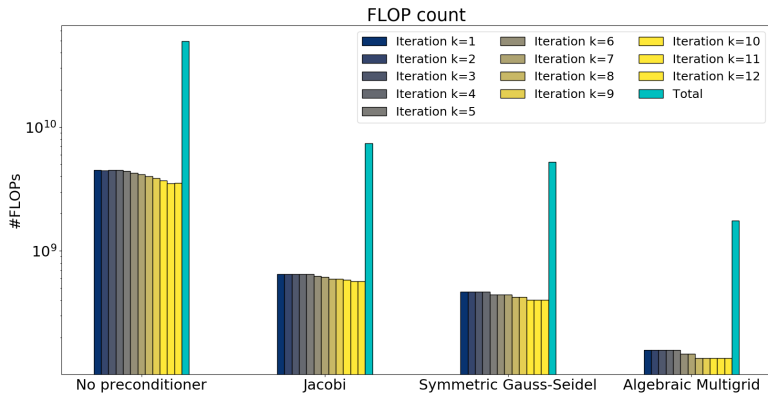
(b) Mesh with a hole $n \approx 10^4$.

For both: Elastic regularization with $\alpha = 5 \cdot 10^3$

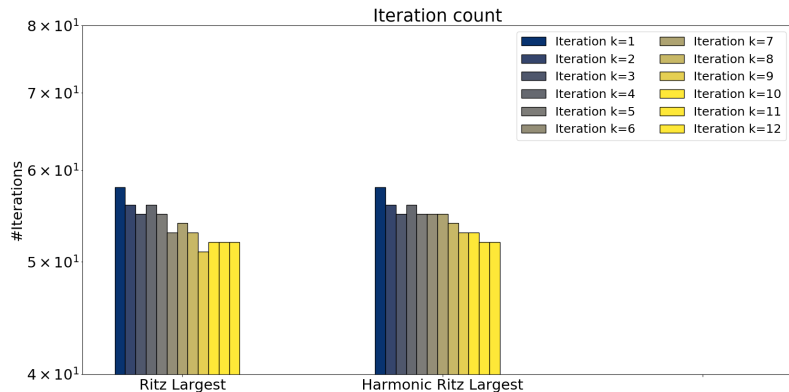
Iteration count vs. Preconditioners



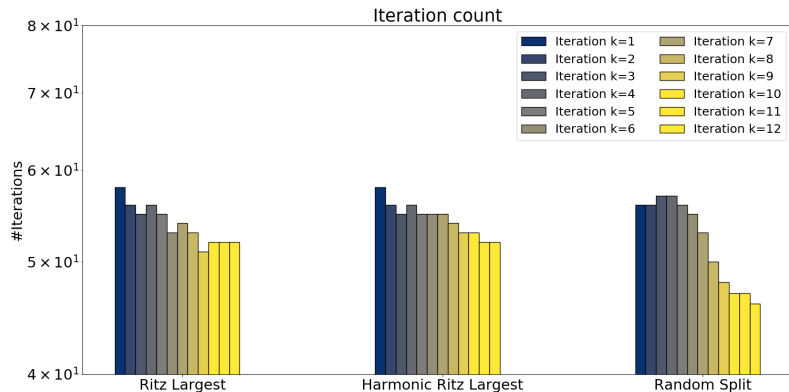
FLOP count vs. Preconditioners



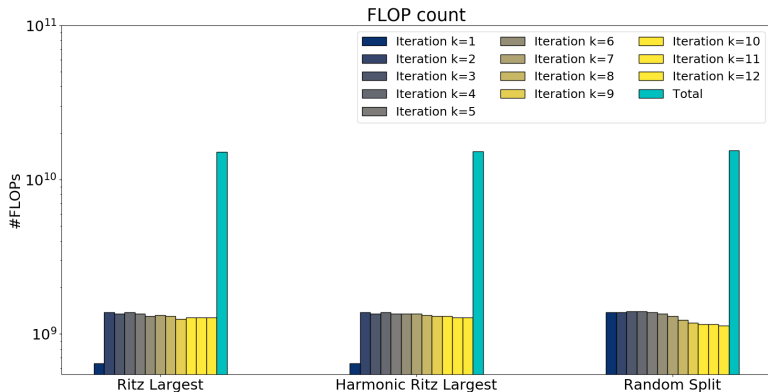
Iteration count vs. Deflation strategy



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Conclusions and perspectives

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- Algebraic preconditioners perform well, especially the algebraic multi-grid,
- Random deflation subspace is potentially interesting compared to standard deterministic deflation strategies.

Perspectives,

- Interested in solving larger problems, with more complex meshes,
- Studying the performance of the preconditioners in this context,
- Combining preconditioning and deflation,
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Thank you for your attention.

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